

2. Implicit Integration Methods.

$$y_{n+1} = y_n + h \int_0^1 y' d\alpha$$

Trick: Shift the Newton backward diff formula by one pt

$$y = y_{n+1} + (\alpha-1)\nabla y_{n+1} + \frac{\alpha(\alpha-1)}{2}\nabla^2 y_{n+1} + \frac{(\alpha-1)\alpha(\alpha+1)}{6}\nabla^3 y_{n+1} + \dots$$

$$y' = y'_{n+1} + (\alpha-1)\nabla y'_{n+1} + \frac{\alpha(\alpha-1)}{2}\nabla^2 y'_{n+1} + \frac{(\alpha-1)\alpha(\alpha+1)}{6}\nabla^3 y'_{n+1} + \dots$$

$$y_{n+1} = y_n + h \int_0^1 y' d\alpha$$

$$= y_n + h \sum_{i=0}^{\infty} a_i \nabla^i y'_{n+1}$$

$$\Rightarrow a_i = \int_0^1 \frac{(\alpha-1)\alpha(\alpha+1)\dots(\alpha+i-2)}{i!} d\alpha$$

$$a_0 = 1$$

$$a_1 = \int_0^1 (\alpha-1) d\alpha = -\frac{1}{2}$$

$$a_2 = \int_0^1 \frac{(\alpha-1)\alpha}{2} d\alpha = -\frac{1}{12}$$

⋮

General formula

$$y_{n+1} = y_n + h \left[1 - \frac{1}{2} \nabla - \frac{1}{12} \nabla^2 - \frac{1}{24} \nabla^3 + \dots \right] y'_{n+1}$$

(1) Backward Euler, Implicit Euler.

$$q = 0$$

$$y_{n+1} = y_n + h y'_{n+1} + O(h^2)$$

$$/ = y_n + h f(y_{n+1}) + O(h^2)$$

$$\frac{y_{n+1} - y_n}{h} = f(y_{n+1}) + O(h).$$

* Implicit methods give

non linear systems of algebraic equations
at each time step.

initial guess.
iteration method.
convergence.

(2) Crank-Nicolson method (Trapezoid rule,
modified Euler, 2nd order Adams-Moulton)

$$q = 1$$

$$y_{n+1} = y_n + h \left[y'_{n+1} - \frac{1}{2} \nabla y'_{n+1} \right] + O(h^3)$$

$$= y_n + \frac{h}{2} [2y'_{n+1} - y'_{n+1} + y'_n] + O(h^3)$$

$$= y_n + \frac{h}{2} [y'_{n+1} + y'_n] + O(h^3)$$

$$= y_n + \frac{h}{2} [f(y_{n+1}) - f(y_n)] + O(h^3)$$

(3) Fourth order Adams-Moulton

$$q=3$$

$$y_{n+1} = y_n + \frac{h}{24} (9y'_{n+1} + 19y'_n - 5y'_{n-1} + y'_{n-2}) + O(h^5)$$

* Problem for $\frac{dy}{dt} = f(y)$

Explicit Euler

$$y_{n+1} = y_n + hf(y_n)$$

1 func eval

Implicit Euler

$$y_{n+1} = y_n + hf(y_{n+1})$$

$$\begin{aligned} &\text{Solve} \\ &R(y_{n+1}) \\ &= y_{n+1} - hf(y_{n+1}) - y_n = 0 \end{aligned}$$

(4) Convergence

Think

- Solution is iterative
- Need initial guess $\{y_{n+1}^{(0)}\}$
- Convergence?

Each implicit method

$$y_{n+1} = h g(y_{n+1}) + w_n \quad \text{subscript: time step}$$

Iterative solution at each time step

$$y_{n+1}^{(0)} \rightarrow \{y_{n+1}^{(k)}\} \rightarrow y_{n+1}^* \text{ Solution}$$

Imagine Fixed point iteration

$$y_{n+1}^{(k+1)} = h g(y_{n+1}^{(k)}) + w_n = F(y_{n+1}^{(k)})$$

$$L = \left| \frac{\partial F}{\partial y_{n+1}} \right| = \left| h \frac{\partial g}{\partial y_{n+1}} \right|$$

For convergence $L < 1$,

true for small enough h

h controls accuracy
stability
convergence for NL eqn

(5) Stability of Implicit Method

$$\frac{dy}{dt} = -\lambda y$$

$$y = y_e + e(t)$$

↓

$$\frac{de}{dt} = -\lambda e$$

i) Implicit Euler

$$e_{n+1} - e_n = -h\lambda e_{n+1}$$

$$\left| \frac{e_{n+1}}{e_n} \right| = \left| \frac{1}{1+h\lambda} \right| \quad \text{always stable}$$

ii) Trapezoid Rule

$$e_{n+1} - e_n = \frac{h}{2} [-\lambda e_{n+1} - \lambda e_n]$$

$$e_{n+1} \left(1 + \frac{h\lambda}{2} \right) = e_n \left(1 - \frac{h\lambda}{2} \right)$$

$$\left| \frac{e_{n+1}}{e_n} \right| = \left| \frac{1 - \frac{h\lambda}{2}}{1 + \frac{h\lambda}{2}} \right| < 1$$

Always stable but if $\frac{h\lambda}{2} > 1$
error oscillates with "n"

3. Predictor corrector method.

(1) Euler / Implicit Euler

Implicit Euler $y_{n+1} = y_n + hf(y_{n+1})$

Predictor:

Euler to generate an initial guess

$$y_{n+1}^P = y_n + hf(y_n)$$

Corrector

$$y_{n+1} = y_n + hf(y_{n+1}^P)$$

P-C algorithm become equivalent to fully implicit method if corrector step is iterated to convergence.

(2) Euler - Predictor / Crank-Nicolson Corrector

Predict $y_{n+1}^P = y_n + hf(y_n)$

Correct $y_{n+1} = y_n + \frac{h}{2} (f(y_{n+1}^P) + f(y_n))$

4. Runge - Kutta method.

$$\frac{dy}{dt} = f(t, y(t))$$

Formula (V -th order)

$$y_{n+1} \equiv y(t_{n+1}) = y_n + \sum_{i=1}^V w_i k_i$$

weighting coeff

$$k_i = hf(t_n + c_i h, y_n + \sum_{j=1}^{i-1} a_{ij} k_j), \quad c_1 \equiv 0$$

$h \equiv t_{n+1} - t_n$ fraction step

coeff $\{c_i\}$, $\{a_{ij}\}$ $\{w_i\}$

Taylor series expansion

$$y_{n+1} = y_n + y_n' h + \frac{h^2}{2} y_n'' + \frac{h^3}{6} y_n''' + \dots$$

$$y_n' = f_n = f(t_n, y_n)$$

$$y_n'' = \left[\frac{d}{dt} f(t, y) \right]_{t_n} = \left[\frac{\partial f}{\partial t} + \frac{\partial f}{\partial y} \frac{dy}{dt} \right]_{t_n}$$

$$= (f_t + f f_y)_{t_n}$$

$$y_n''' = [f_{tt} + f_{tfy} + f_{fty} + f_{ty} f + f_y^2 f + f_{fyy}]_{t_n}$$

$$y_{n+1} = y_n + h f_n + \frac{h^2}{2} (f_t + f f_y)_n$$

$$+ \frac{h^3}{6} (f_{tt} + f_{tfy} + 2f_{fty} + f f_y^2 + f^2 f_{yy})_n \quad (A)$$

$$k_1 = h f(t_n + c_1 h, y_n) = h f(t_n, y_n) = h f_n$$

$$k_2 = h f(t_n + c_2 h, y_n + a_{21} k_1)$$

$$= h f(t_n + c_2 h, y_n + a_{21} h f_n)$$

expansion
in terms
of h

$$\approx h f(t_n, y_n) + h^2 [f_t c_2 + f_y a_{21} f_n] t_n$$

$$+ h^3 \left[\frac{c_2^2}{2} f_{tt} + f_{ty} c_2 \cdot a_{21} f_n + \frac{a_{21}^2}{2} f_n^2 f_{yy} \right] t_n$$

$$k_3 = h f(t_n + c_3 h, y_n + a_{31} k_1 + a_{32} k_2)$$

$$= h f(t_n, y_n) + h [f_t \cdot c_3 h + f_y (a_{31} k_1 + a_{32} k_2)] t_n$$

$$+ h \left[\frac{c_3^2 h^2}{2} f_{tt} + f_{ty} c_3 h (a_{31} k_1 + a_{32} k_2) + f_{yy} \frac{(a_{31} k_1 + a_{32} k_2)^2}{2} \right]$$

$$= h f(t_n, y_n) + h^2 (c_3 f_t + a_{31} f_y f_n + a_{32} f_y f_n) t_n$$

$$+ h^3 (f_y a_{32} (f_t c_2 + f_y a_{21} f_n))$$

$$+ \frac{c_3^2}{2} f_{tt} + c_3 f_{ty} (a_{31} + a_{32}) f_n$$

$$+ \frac{1}{2} (a_{31} + a_{32})^2 f_n^2 f_{yy}] t_n$$

$$\begin{aligned}
y_{n+1} &= y_n + w_1 k_1 + w_2 k_2 + w_3 k_3 \\
&= y_n + w_1 h f_n + w_2 h f_n + w_2 h^2 (f_t c_2 + a_{21} f f_y) \\
&\quad + w_2 h^3 \left[\frac{c_2^2}{2} f_{tt} + f f_y c_2 a_{21} f + \frac{a_{21}^2}{2} f^2 f_{yy} \right] \\
&\quad + w_3 h f_n + w_3 h^2 (c_3 f_t + a_{31} f f_y + a_{32} f f_y) + w_3 h^3 (\dots) + \dots \\
&= y_n + h (w_1 + w_2 + w_3 + \dots) f_n \\
&\quad + h^2 f_t (c_2 w_2 + c_3 w_3 + \dots) \\
&\quad + h^2 f f_y (w_2 a_{21} + w_3 (a_{31} + a_{32}) + \dots) \\
&\quad + O(h^3) \tag{B}
\end{aligned}$$

Compare (A) & (B)

$$w_1 + w_2 + \dots + w_r = 1.0$$

$$w_2 c_2 + w_3 c_3 + \dots + w_r c_r = 0.5$$

$$w_2 a_{21} + w_3 (a_{31} + a_{32}) + \dots = 0.5$$

$$w_r \sum_{i=1}^{r-1} a_{ri}$$

i) $V=2$

$$w_1 + w_2 = 1.0$$

$$\left. \begin{aligned} w_2 c_2 &= 0.5 \\ w_2 a_{21} &= 0.5 \end{aligned} \right\} \rightarrow c_2 = a_{21}$$

3 eqns, 4 unknowns.

a) $c_2 = \frac{1}{2}$

$$w_2 = 1, a_{21} = \frac{1}{2}, w_1 = 0.$$

$$k_1 = h f_n$$

$$k_2 = h f(t_n + 0.5h, y_n + 0.5h f_n)$$

predictor-corrector scheme that uses f evaluated at the Euler approximation to the midpoint between t_n & t_{n+1}

$$y_{n+1} = y_n + h f(t_n + 0.5h, y_n + 0.5h f_n)$$

Midpoint Scheme.

b) $C_2 = 1$

$$a_{21} = 1, w_2 = \frac{1}{2}, w_1 = \frac{1}{2}$$

$$k_1 = h f_n$$

$$k_2 = h f(t_n + h, y_n + h f_n)$$

$$y_{n+1} = y_n + \frac{h}{2} (f_n + f(t_n + h, y_n + h f_n))$$

equivalent to Euler predictor / Trapezoid rule corrector.

ii) $V = 3$

1. $w_1 + w_2 + w_3 = 1$

2. $w_2 c_2 + w_3 c_3 = \frac{1}{2}$

3. $a_{21} w_2 + w_3 a_{31} + w_3 a_{32} = \frac{1}{2}$

4. $c_2 a_{21} w_2 + c_3 (a_{31} + a_{32}) w_3 = \frac{1}{3}$

5. $\frac{1}{2} c_2^2 w_2 + \frac{1}{2} c_3^2 w_3 = \frac{1}{6}$

6. $\frac{1}{2} a_{21}^2 w_2 + \frac{1}{2} (a_{31} + a_{32})^2 w_3 = \frac{1}{6}$

7. $a_{21} a_{31} w_3 = \frac{1}{6}$

8. $c_2 a_{31} w_3 = \frac{1}{6}$

8 equations \rightarrow only 6 are independent

8 unknowns $w_1, w_2, w_3,$
 c_2, c_3
 a_{21}, a_{31}, a_{32}

two constants at will. \rightarrow Third-order Runge-Kutta method

(iv) $V=4$ Runge-Kutta-Gill method.

$$y_{n+h} = y_n + \frac{1}{6} (k_1 + k_4) + \frac{1}{3} (bk_2 + dk_3)$$

$$k_1 = hf_n$$

$$k_2 = hf(t_n + \frac{1}{2}h, y_n + \frac{1}{2}k_1)$$

$$k_3 = hf(t_n + \frac{1}{2}h, y_n + ak_1 + bk_2)$$

$$k_4 = hf(t_n + h, y_n + ck_2 + dk_3)$$

$$a = \frac{\sqrt{2}-1}{2}, \quad b = \frac{2-\sqrt{2}}{2}$$

$$c = -\frac{\sqrt{2}}{2}, \quad d = 1 + \frac{\sqrt{2}}{2}$$