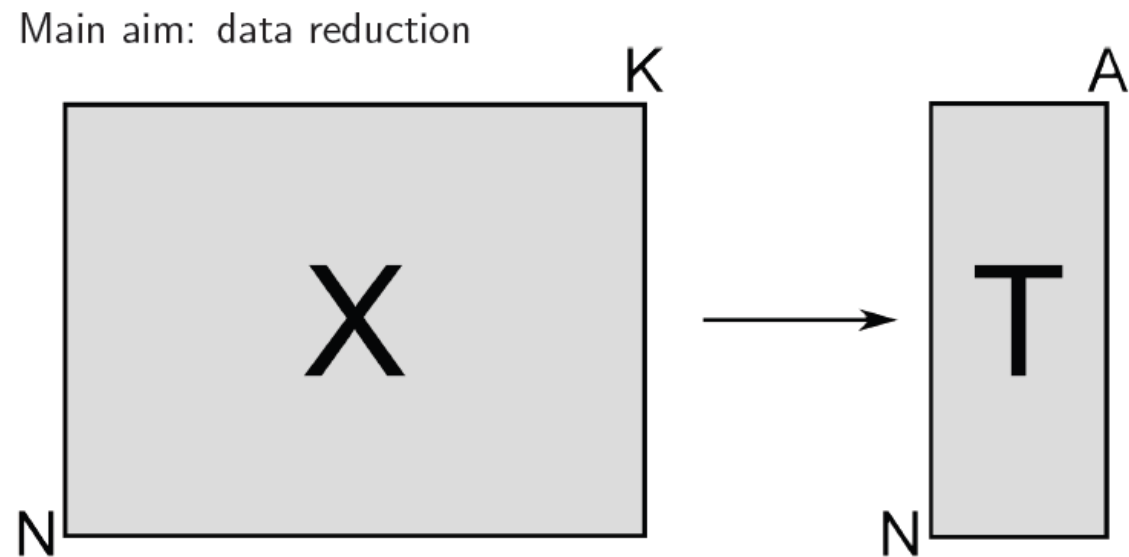


## 2. Principal Component Analysis

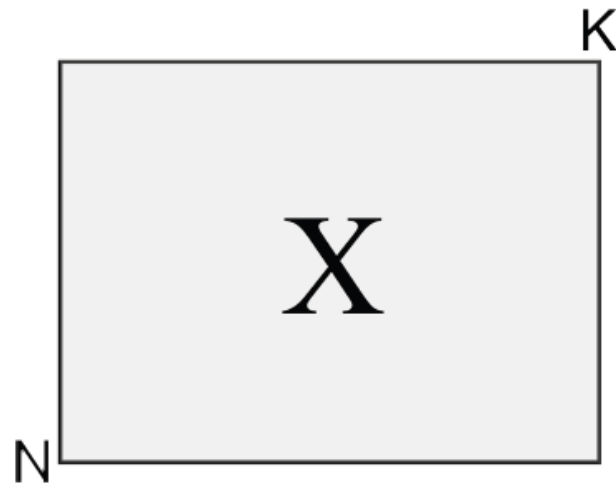
- Visualizing multivariate data
- Geometric interpretation of PCA
- Mathematical interpretation
- Example(s)

# Principal Component Analysis



# Visualizing Multivariate Data

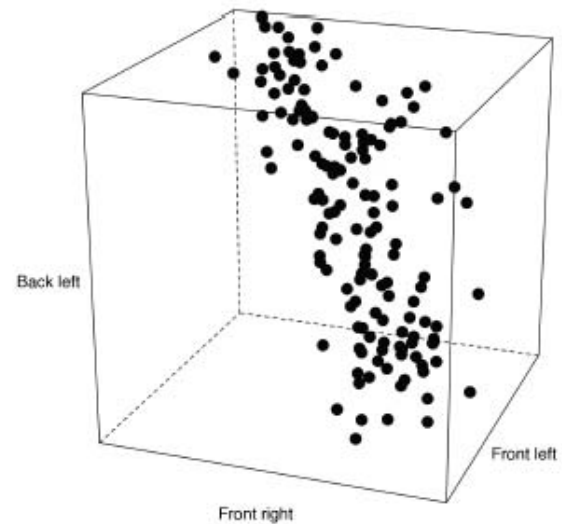
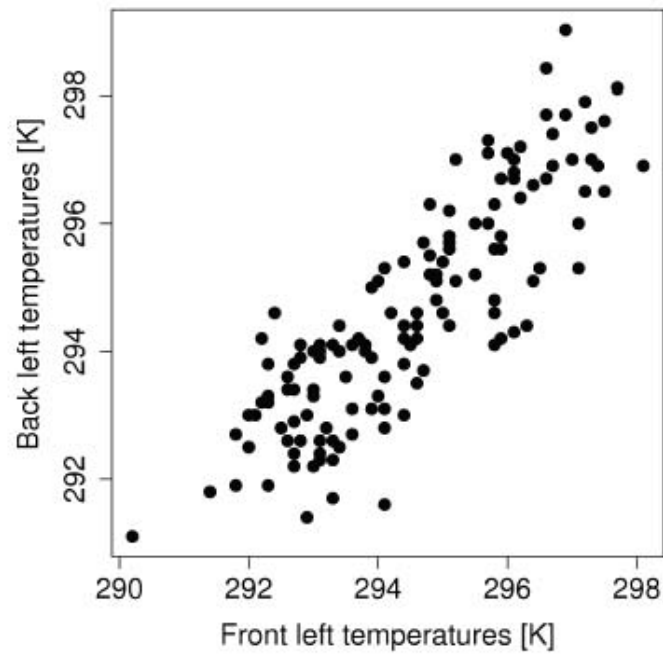
- ▶ PCA considers a single matrix:  $\mathbf{X}$



- ▶  $N$  observations
- ▶  $K$  variables
- ▶ Which variables go in  $\mathbf{X}$ ?

# Visualizing Multivariate Data

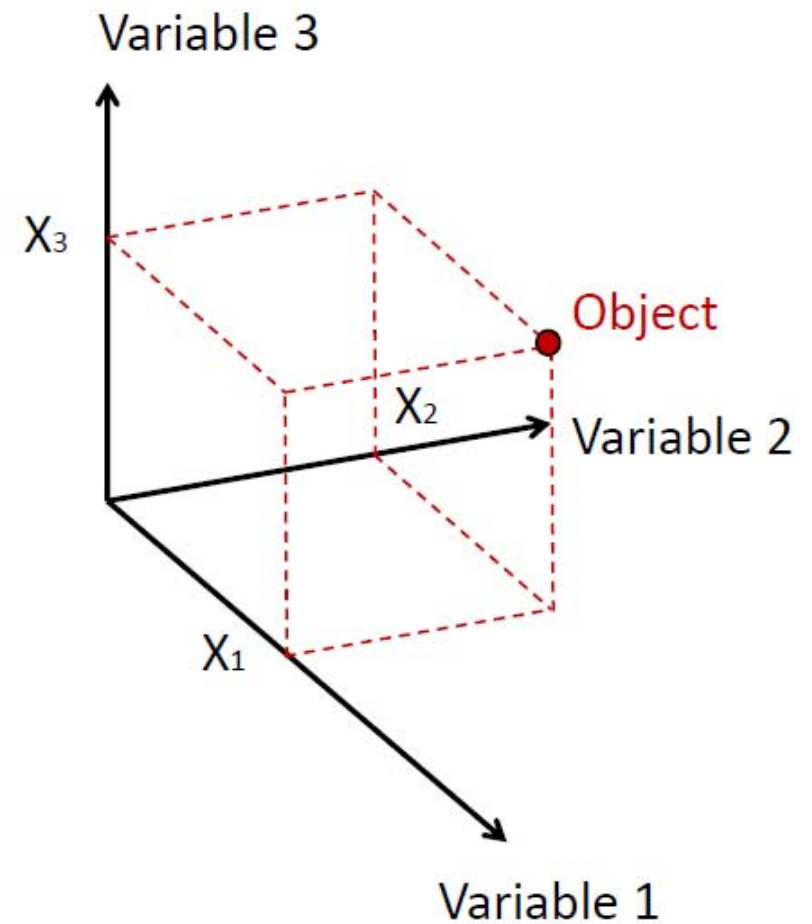
*Temperature example*



# Geometric Interpretation

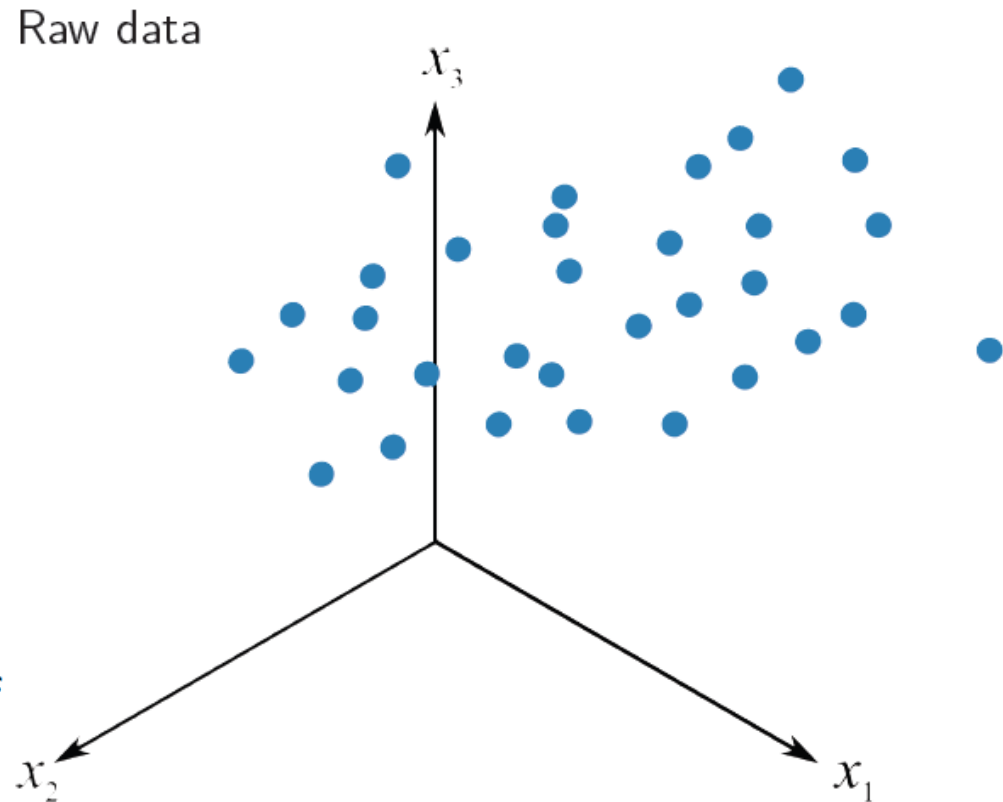
- Each variable defines an axis. A coordinate system can be made using all variables, called the variable space.
- Each object is a row in the data table (matrix) and is visualised as a point in the variable space.

	Variable 1	Variable 2	Variable 3
Object 1			
Object 2			
Object 3			
Object 4			



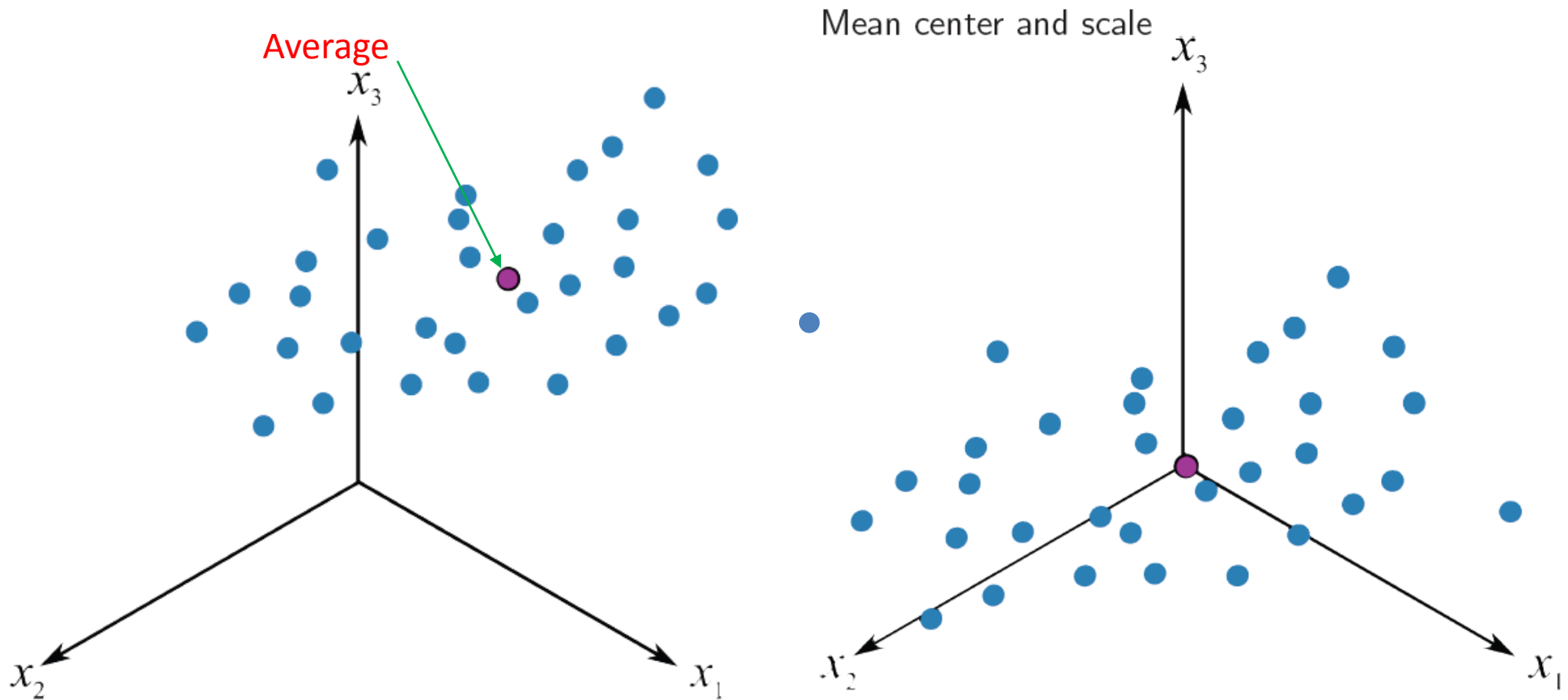
# Geometric Interpretation

- Each sample / object is represented as a point in the variable space.
- The whole data table constitutes a swarm of points in the variable space.
- We would like to find out more about the structure of this swarm.



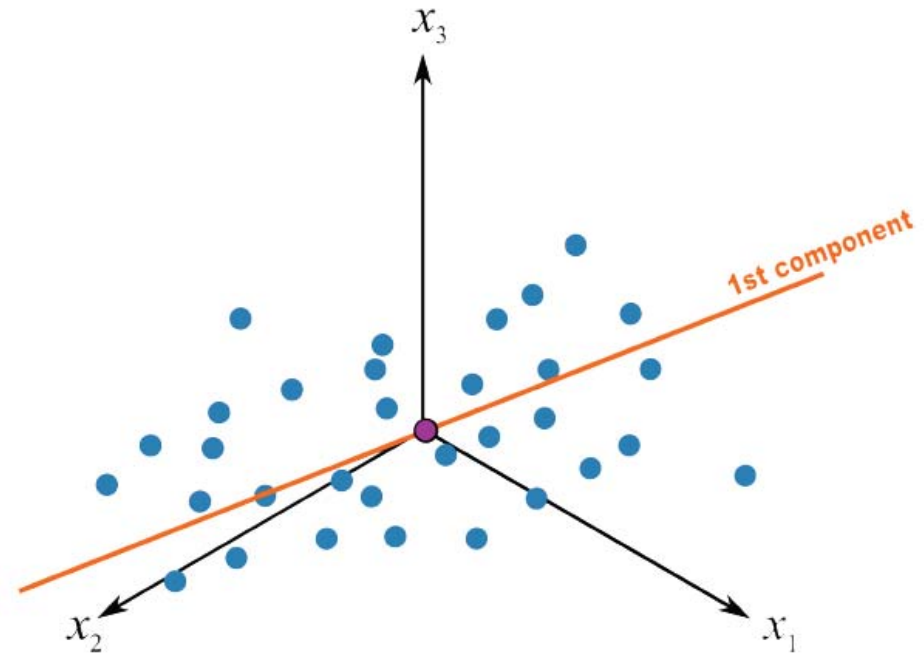
# Geometric Interpretation

- In many cases, the swarm of points has a specific shape in some direction.



# Geometric Interpretation

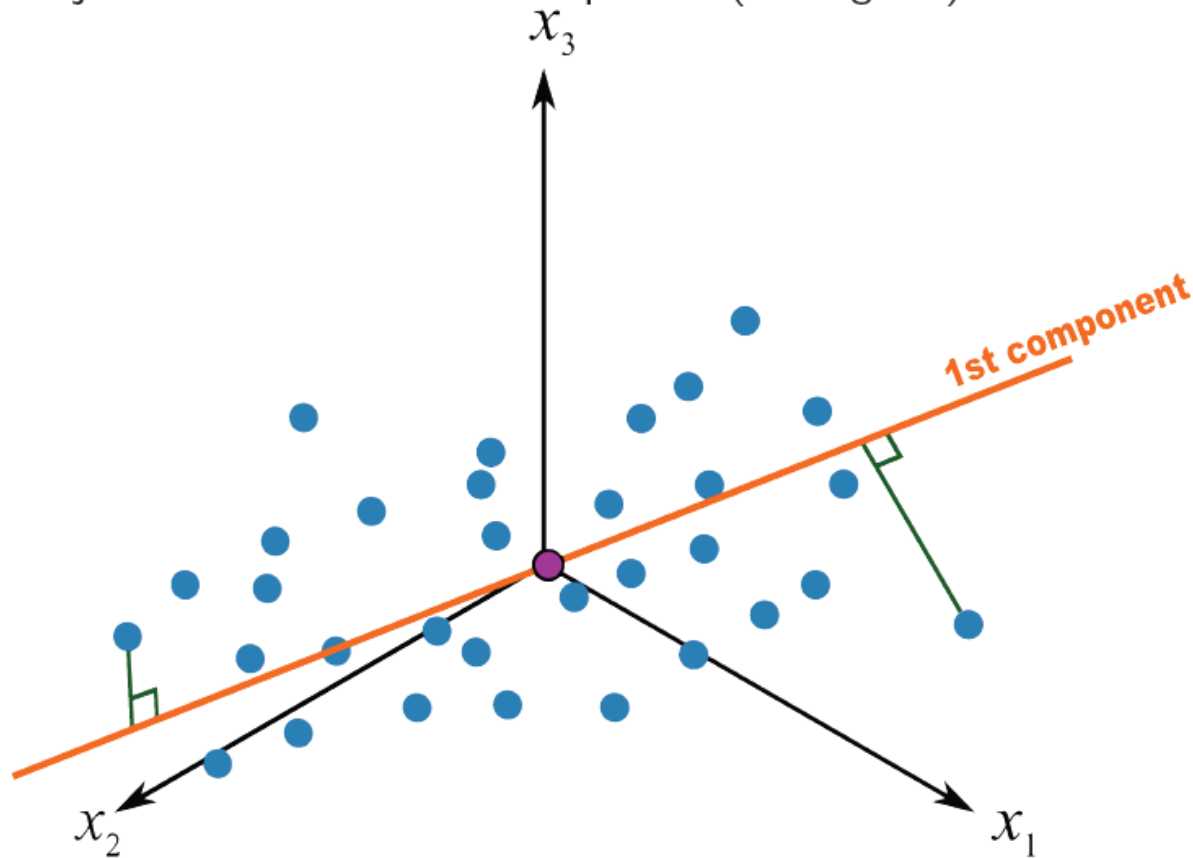
- By picking the direction of largest elongation, this direction will pass through the center of the swarm.
- This line is called the first **principal component (PC1)** and points in the direction of the maximum data variation.





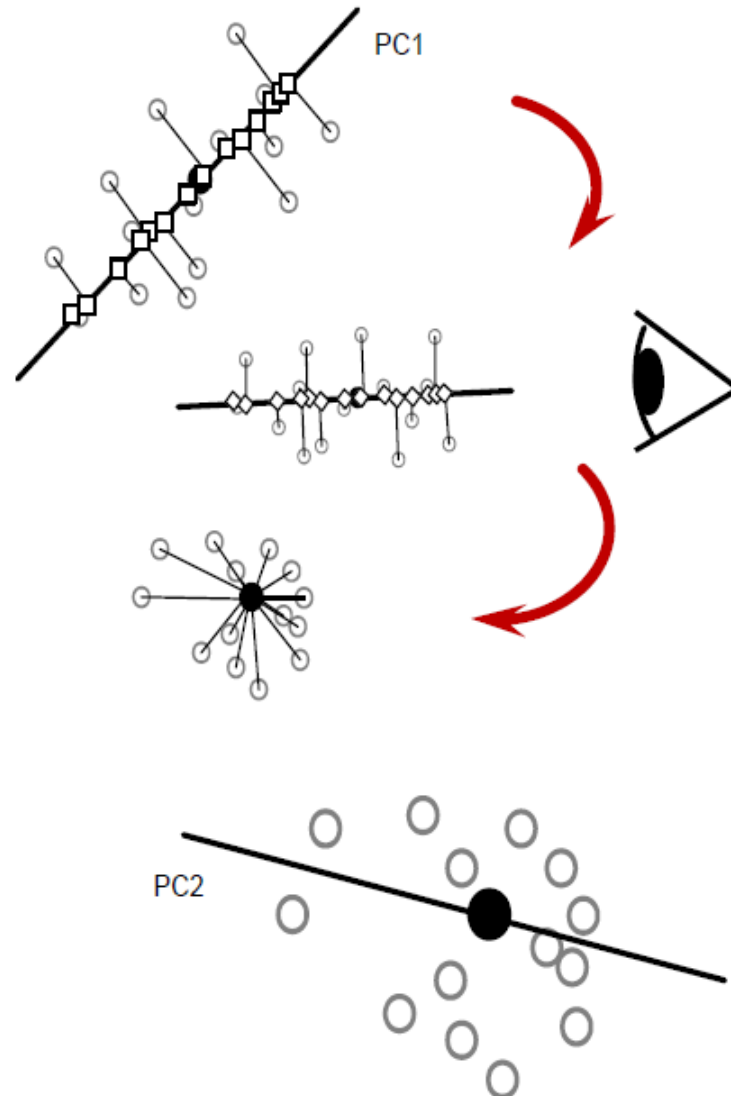
# Geometric Interpretation

Project observations onto component (90 degrees)



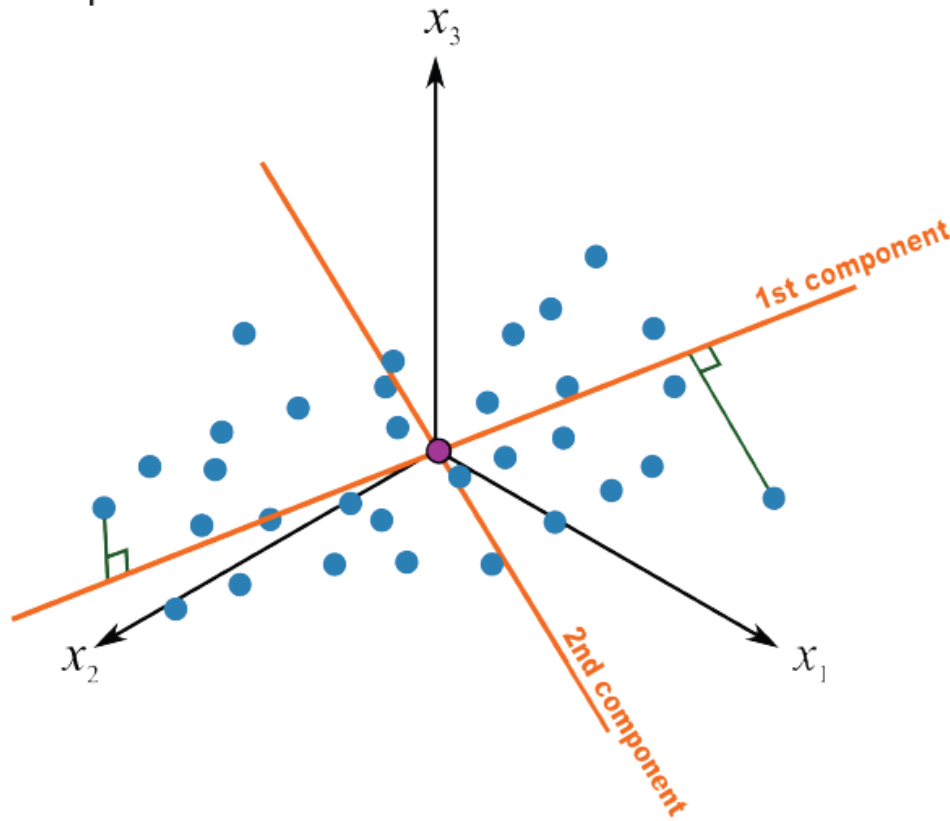
# Geometric Interpretation

- The first principal component may not be enough to describe the data variation.
- By projecting the samples onto the new coordinate system, there is still unexplained variance (combination of the individual **residuals**)
- If we repeat the projection process in the remaining part of the space, we will find the second **principal component (PC2)**.



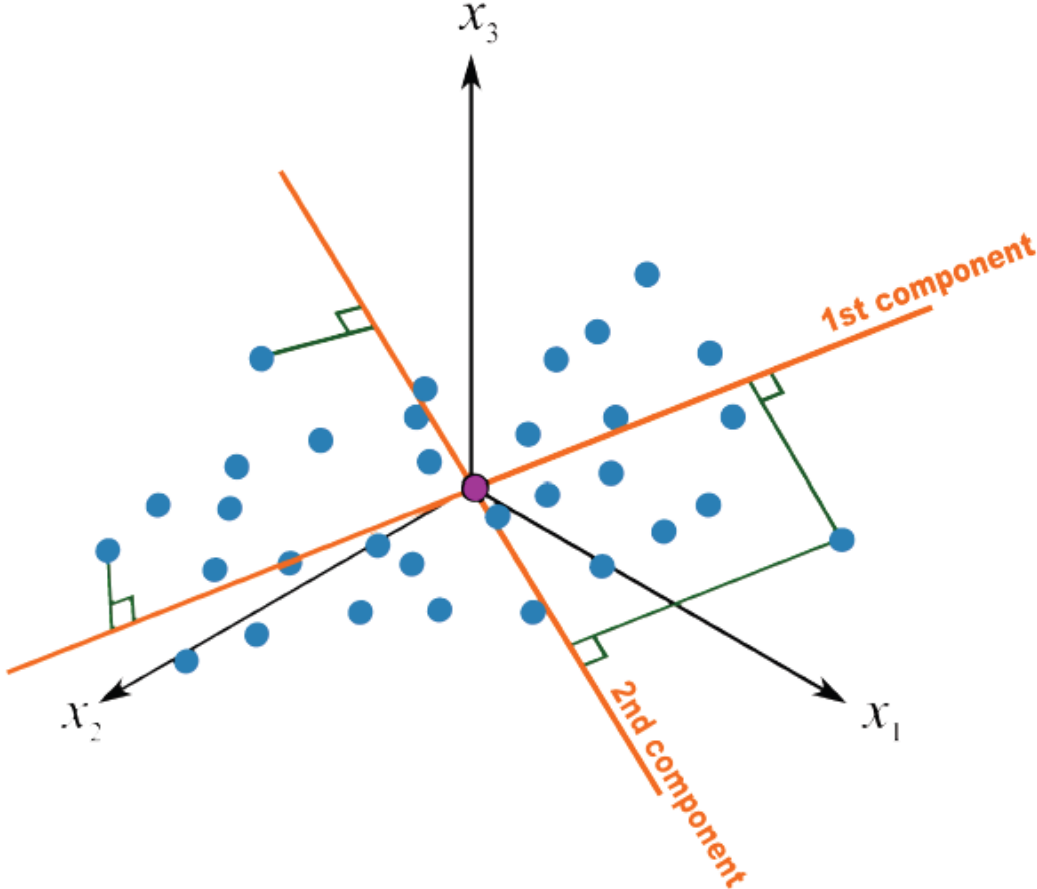
# Geometric Interpretation

Second component: best-fit line; perpendicular to 1st component



# Geometric Interpretation

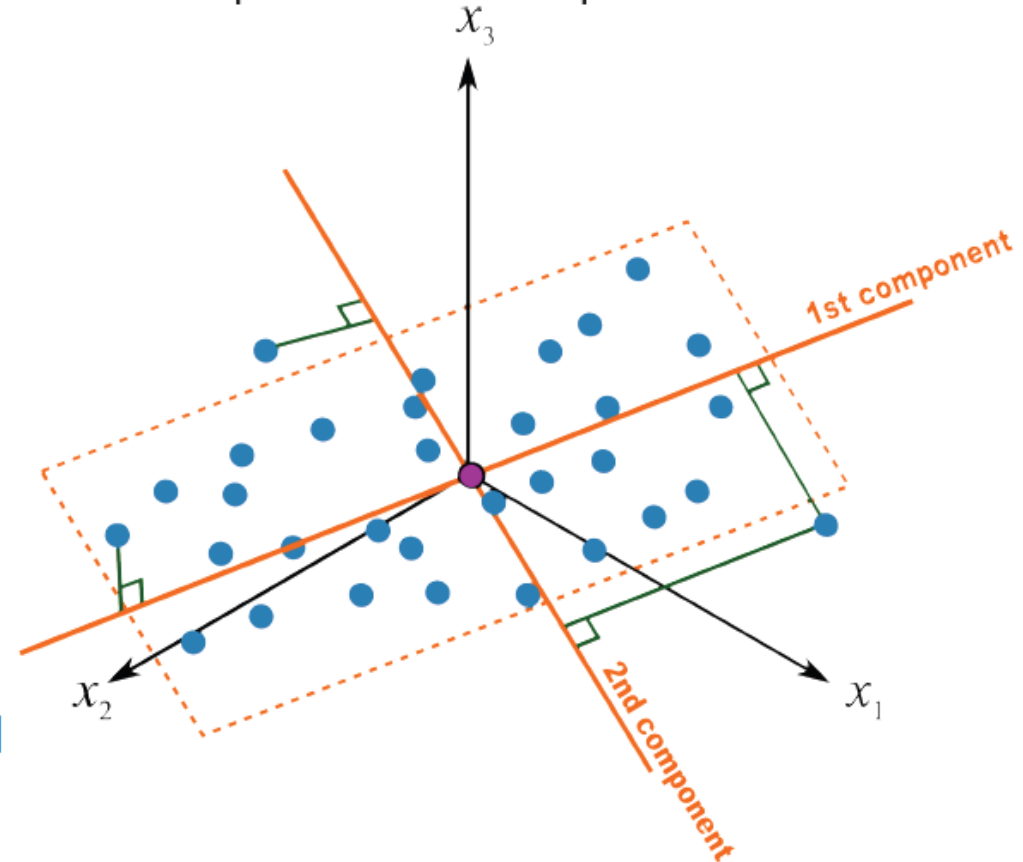
Second component: project onto second component



# Geometric Interpretation

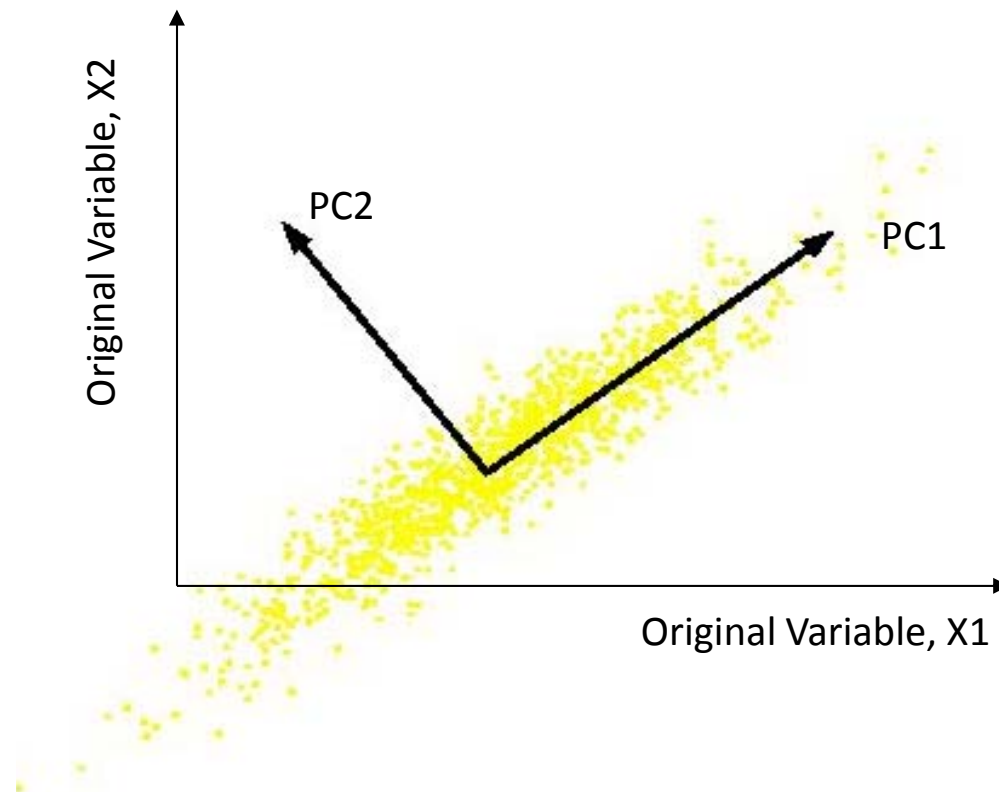
- With 2 principal components we can build a plane onto which the projections of the swarm lie closer yet to the original variable space.
- We have found the 2-dimensional 'window' which best describes the data.
- The process can be continued to find more PCs.

The 2 components create a plane



# Geometric Interpretation

- In summary,
  - PCA finds a few orthogonal axes of greatest variance in data.



# Geometric Interpretation

- New latent variables are linear combinations of the original variables.

$$PC1 = a_1 X1 + a_2 X2 + a_3 X3$$

$$X = \text{Mean} + b_1 PC1 + b_2 PC2 + \text{Error}$$

Constraints :

- Maximise the dispersion of samples along the latent variables (the variance)
- Orthogonality

# Mathematical Derivation

What has this done?

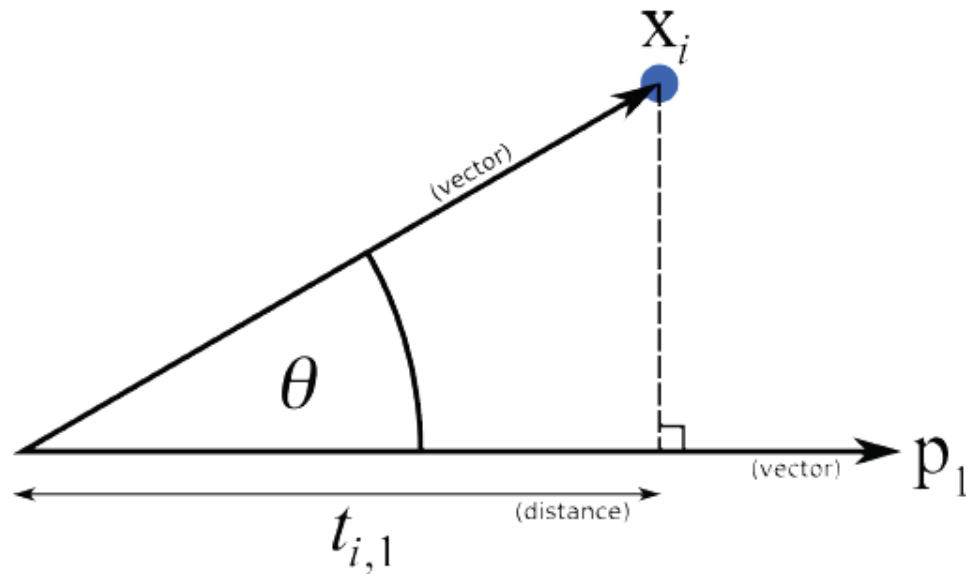
Break  $\mathbf{X}$  down into 2 parts:

- ▶ projected points "*on the plane*"
- ▶ residual distance "*off the plane*"



# Mathematical Derivation

- From linear algebra (or engineering mathematics),



$$\cos \theta = \frac{\text{adjacent length}}{\text{hypotenuse}} = \frac{t_{i,1}}{\|\mathbf{x}_i\|}$$

$$\text{and also } \cos \theta = \frac{\mathbf{x}_i^T \mathbf{p}_1}{\|\mathbf{x}_i\| \|\mathbf{p}_1\|}$$

$$\frac{t_{i,1}}{\|\mathbf{x}_i\|} = \frac{\mathbf{x}_i^T \mathbf{p}_1}{\|\mathbf{x}_i\| \|\mathbf{p}_1\|}$$

$$t_{i,1} = \mathbf{x}_i^T \mathbf{p}_1$$

$$(1 \times 1) = (1 \times K)(K \times 1)$$

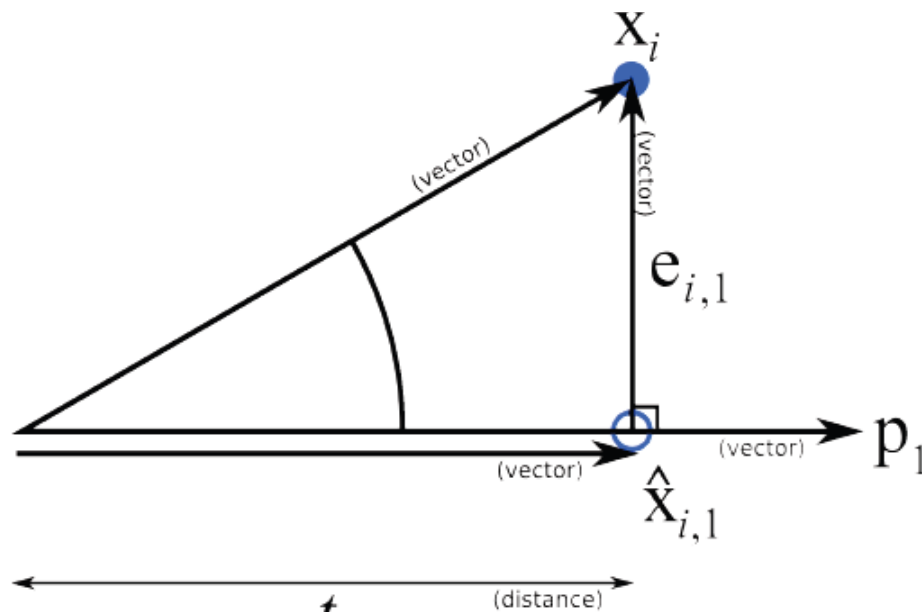
# Mathematical Derivation

$$\begin{aligned}t_{i,1} &= \mathbf{x}_i^T \mathbf{p}_1 \\ &= x_{i,1}p_{1,1} + x_{i,2}p_{2,1} + \dots + x_{i,k}p_{k,1} + \dots + x_{i,K}p_{K,1}\end{aligned}$$

- ▶  $K$  separate terms: added up (i.e. linear combination) to give  $t_1$
- ▶ Entire data set:  $\mathbf{T} = \mathbf{XP}$

## Predicted value for each observations

- $\hat{\mathbf{x}}_i$  : projected version of  $\mathbf{x}_i$



$$\begin{aligned} \hat{\mathbf{x}}_{i,1}^T &= t_{i,1} \mathbf{p}_1^T \\ (1 \times K) &= (1 \times 1)(1 \times K) \end{aligned}$$

# Predicted value for each observations

Residual vector:

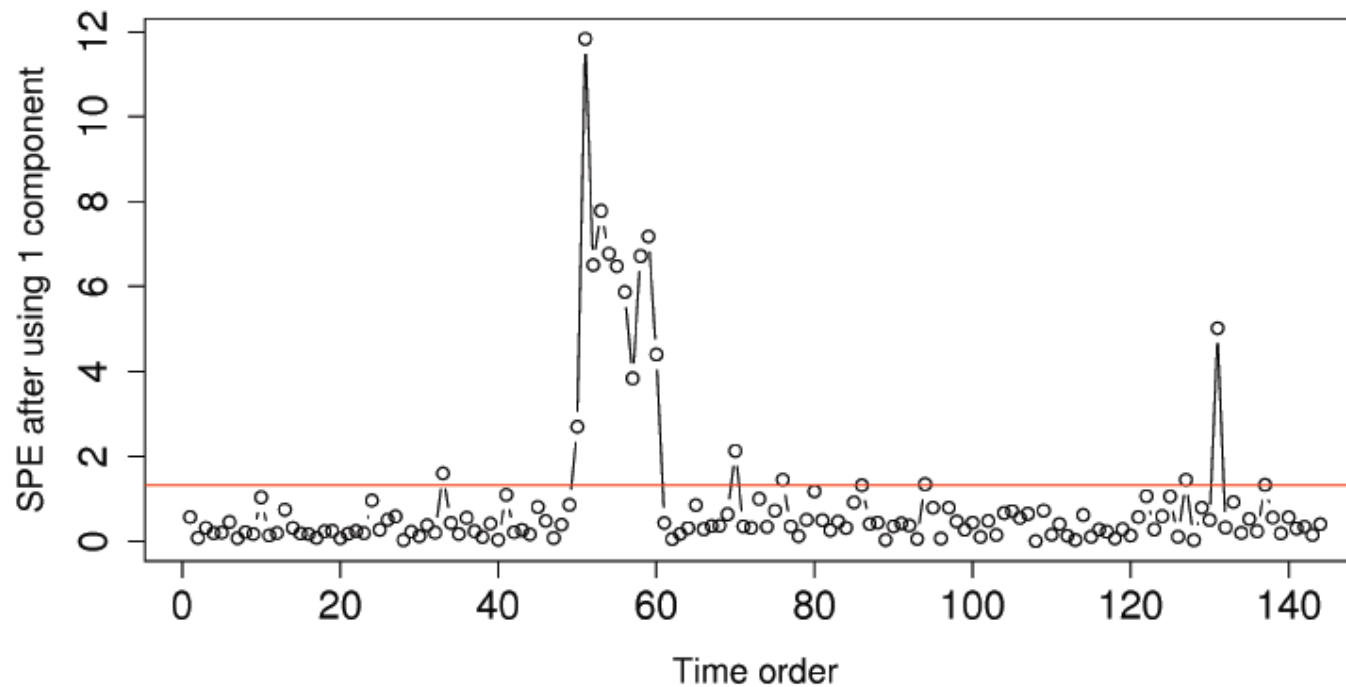
$$\begin{aligned} \mathbf{e}_{i,A}^T &= \mathbf{x}_i^T - \hat{\mathbf{x}}_{i,A}^T \\ (1 \times K) &= (1 \times K) - (1 \times K) \end{aligned}$$

Residual distance:

$$\begin{aligned} \text{SPE}_i &= \sqrt{\mathbf{e}_{i,A}^T \mathbf{e}_{i,A}} \\ (1 \times 1) &= (1 \times K)(K \times 1) \end{aligned}$$

# Square Prediction Error

- ▶  $\mathbf{e}'_{i,A} = \mathbf{x}'_i - \widehat{\mathbf{x}}'_{i,A}$
- ▶  $\text{SPE}_i = \sqrt{e_{i,1}^2 + e_{i,2}^2 + \dots + e_{i,K}^2}$
- ▶ Smallest SPE:  $\text{SPE}_i = 0$
- ▶ Calculate 95% or 99% confidence limit

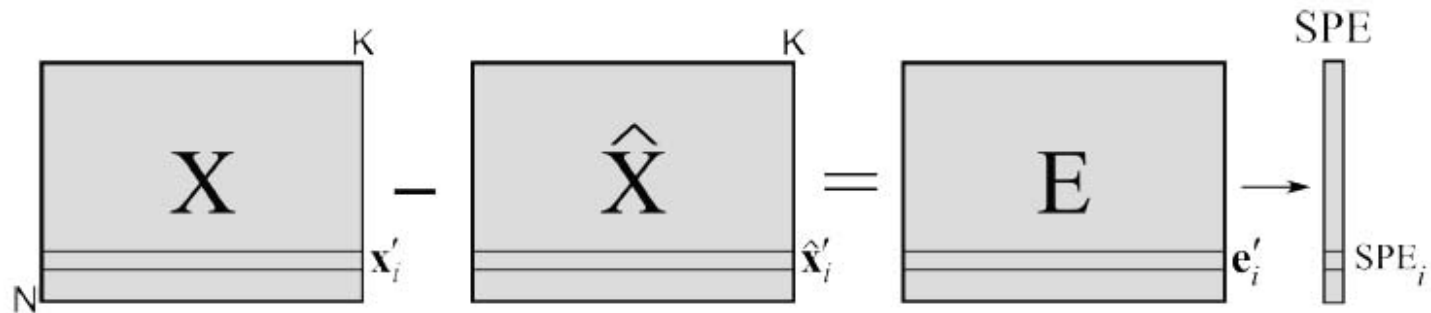


# Square Prediction Error

Distance from each observation to the model's plane:

- ▶ Does model explain that point well?  $SPE=0$
- ▶ If  $SPE > 95\%$  limit:
  - ▶ poorly explained by the model
  - ▶ something new in this observation
  - ▶ new phenomenon?

# Square Prediction Error



▶  $e_i' = \mathbf{x}_i' - \hat{\mathbf{x}}_i'$

▶  $SPE_i = \sqrt{e_{i,1}^2 + e_{i,2}^2 + \dots + e_{i,K}^2}$

$e_i' =$   
 $[(x_{i,1} - \hat{x}_{i,1}) \quad (x_{i,2} - \hat{x}_{i,2}) \quad \dots \quad (x_{i,k} - \hat{x}_{i,k}) \quad \dots \quad (x_{i,K} - \hat{x}_{i,K})]$

# Column Residual

- ▶ SPE is the row residual for  $\mathbf{X}$
- ▶ Residuals also calculated for each column

$$\begin{matrix} & & & K \\ & & & | \\ N & \mathbf{X} & - & \hat{\mathbf{X}} & = & \mathbf{E} \\ & & & | \\ & & & K \\ & & & | \\ & & & \mathbf{e}_k \longrightarrow R_k^2 \end{matrix}$$

- ▶ How well each column is explained by the model



# Column Residual

- ▶ Remember  $R^2 = \frac{\text{variance explained by model}}{\text{initial variance}}$
- ▶  $R_k^2 = \frac{\text{Var}(\hat{\mathbf{x}}_k)}{\text{Var}(\mathbf{x}_k)}$
- ▶ The  $R_k^2$  value:
  - ▶ is 0.0 when there are no components
  - ▶ increases for every every component added

# Whole Matrix Residual

- ▶  $\mathbf{X} = \mathbf{TP}' + \mathbf{E} = \hat{\mathbf{X}} + \mathbf{E}$
- ▶ How well does the model fit the data?
- ▶  $R^2 = \frac{\text{Var}(\hat{\mathbf{X}})}{\text{Var}(\mathbf{X})}$ 
  - ▶  $R^2 = 0.0$  when there are no components
  - ▶  $R^2$  increases with every component added
  - ▶  $R^2_{a=0} > R^2_{a=1} > R^2_{a=2} > \dots > R^2_{a=A} = 1.0$

# More about direction vectors

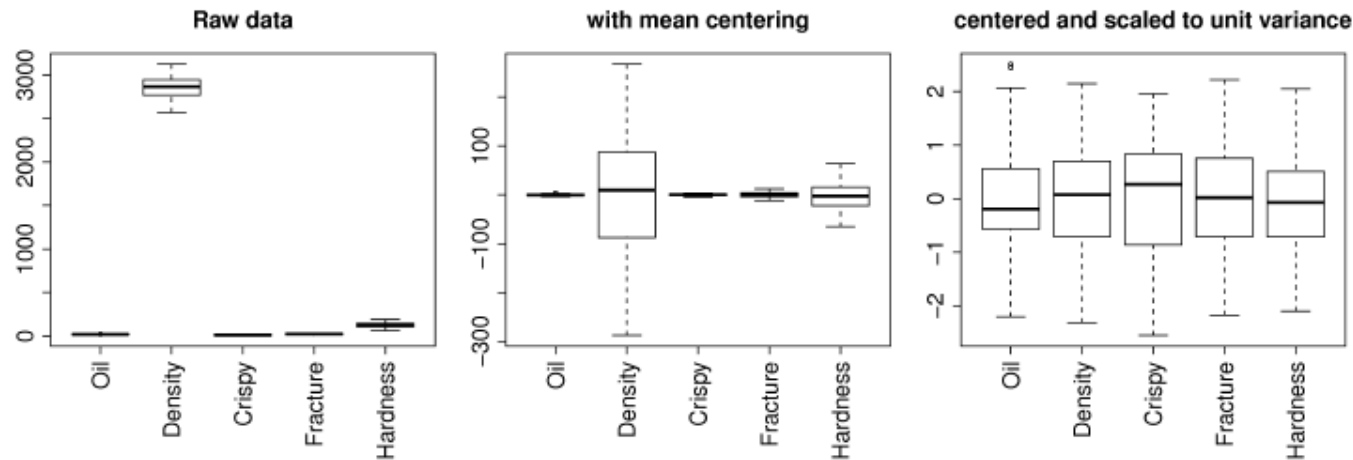
- ▶ "Direction vectors" = "Loadings"
- ▶ Link between the real-world and the latent-variable world

$$\mathbf{T} = \mathbf{XP}$$
$$(N \times A) = (N \times K)(K \times A)$$

※ Statistically, loading vectors are eigenvectors of  $X^T X$ .  
Then how about eigenvalues?

# Preprocessing

## Pre-processing the data: center and scale



- ▶ Centering:  $\mathbf{x}_{k,\text{center}} = \mathbf{x}_{k,\text{raw}} - \text{mean}(\mathbf{x}_{k,\text{raw}})$
- ▶ Scaling:  $\mathbf{x}_k = \frac{\mathbf{x}_{k,\text{center}}}{\text{standard deviation}(\mathbf{x}_{k,\text{center}})}$
- ▶ Does not change relationships between variables.

Remember

$$Z = \frac{X - \mu}{\sigma} \quad ?$$

# More on preprocessing Data

- ▶ Modifies the columns of  $X$  before building the model
- ▶ Center
- ▶ Scale
- ▶ Add transformations:
  - ▶ use  $\log(T)$  instead of temperature,  $T$
  - ▶ use  $1/P$  instead of pressure,  $P$
  - ▶ use  $\sqrt{F}$  instead of flow,  $F$

Add extra columns to  $X$ :

- ▶ heat balance
- ▶ dimensionless numbers
- ▶ square terms:  $x_1^2, x_2^2, \dots$
- ▶ interaction terms:  $x_1x_2, x_1x_3, x_2x_3 \dots$

# How is PCA calculated?

- ▶ Eigenvalue decomposition
  - ▶ loadings are the eigenvectors of  $\mathbf{X}'\mathbf{X}$ .
  - ▶ once you have the eigenvectors, then  $\mathbf{T} = \mathbf{XP}$
  - ▶ eigenvalues are the variances of the scores,  $s_a^2$
- ▶ Singular value decomposition
  - ▶  $\mathbf{X} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}' = \mathbf{TP}'$
  - ▶ scores,  $\mathbf{T} = \mathbf{U}\mathbf{\Sigma}$  and the loadings,  $\mathbf{P} = \mathbf{V}$

# How is PCA calculated?

- ▶ Non-linear iterative partial least-squares (NIPALS) algorithm
  - ▶ One component at a time
  - ▶ Handles missing data
  - ▶ Iterative; it always converges, but slow sometimes
  - ▶ Also called the Power algorithm
  - ▶ Excellent on large data sets
  - ▶ Google used this algorithm for their first search engine (called PageRank)

More details next.

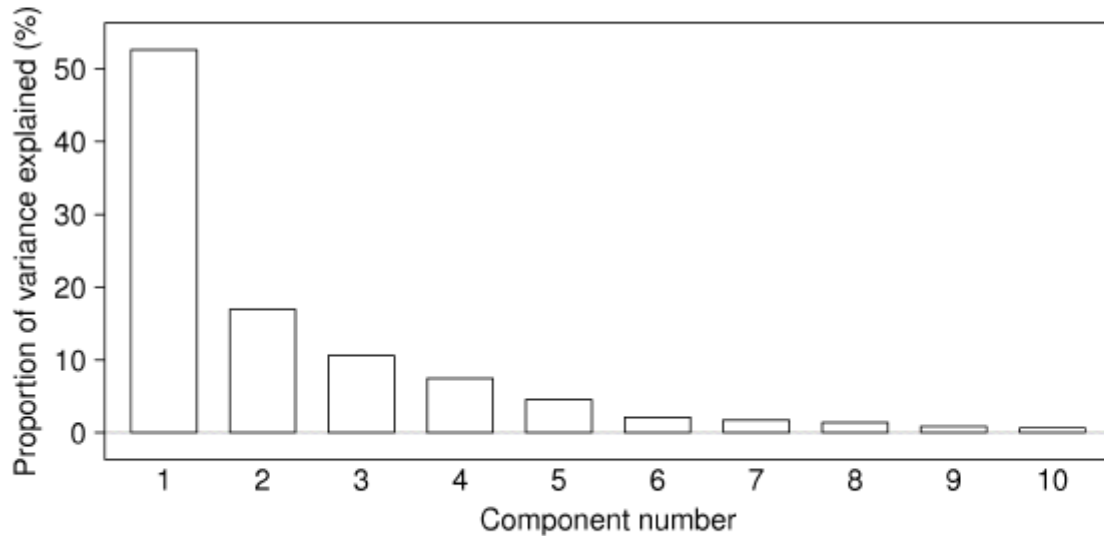
# How many components?

- ▶ Eigenvalues

- ▶ sum of the eigenvalues =  $\sum_a^{a=K} \lambda_a = K$

- ▶ keep adding components as long as  $\lambda_a > 1$

- ▶ Plot  $R^2$  for each component



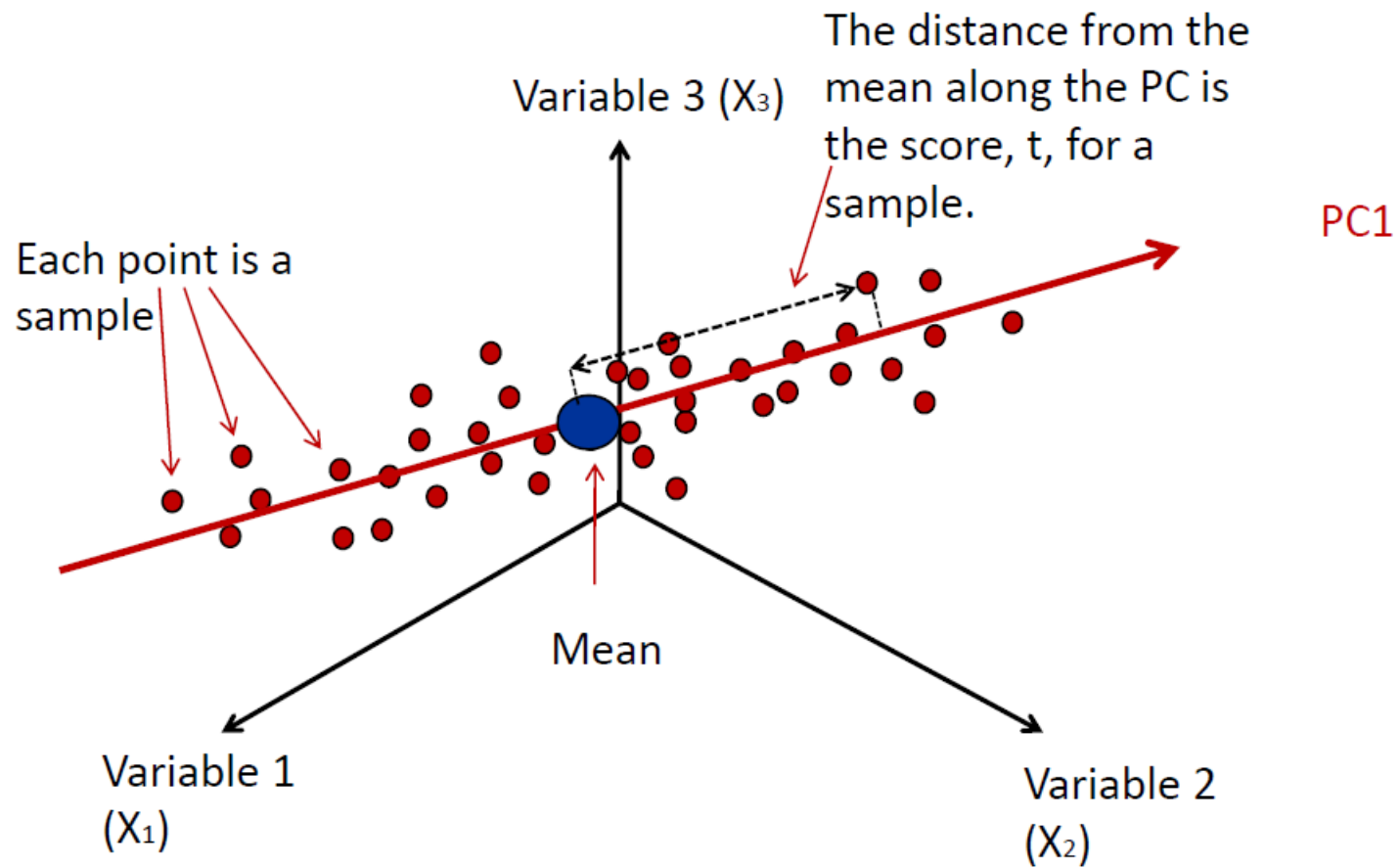
Called scree plot

- ▶ Use cross-validation



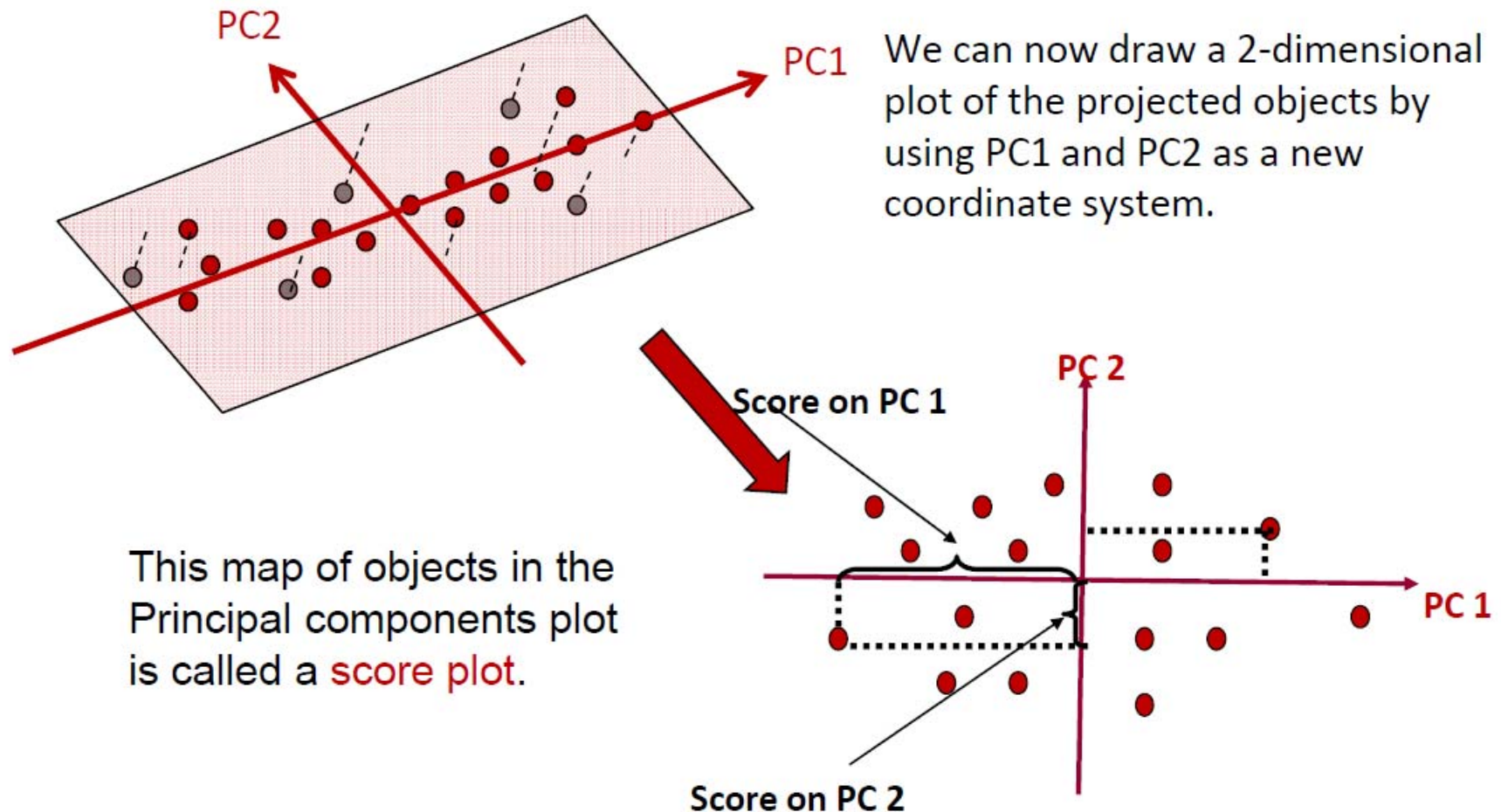
# Review of PCA

- What is score?



# Review of PCA

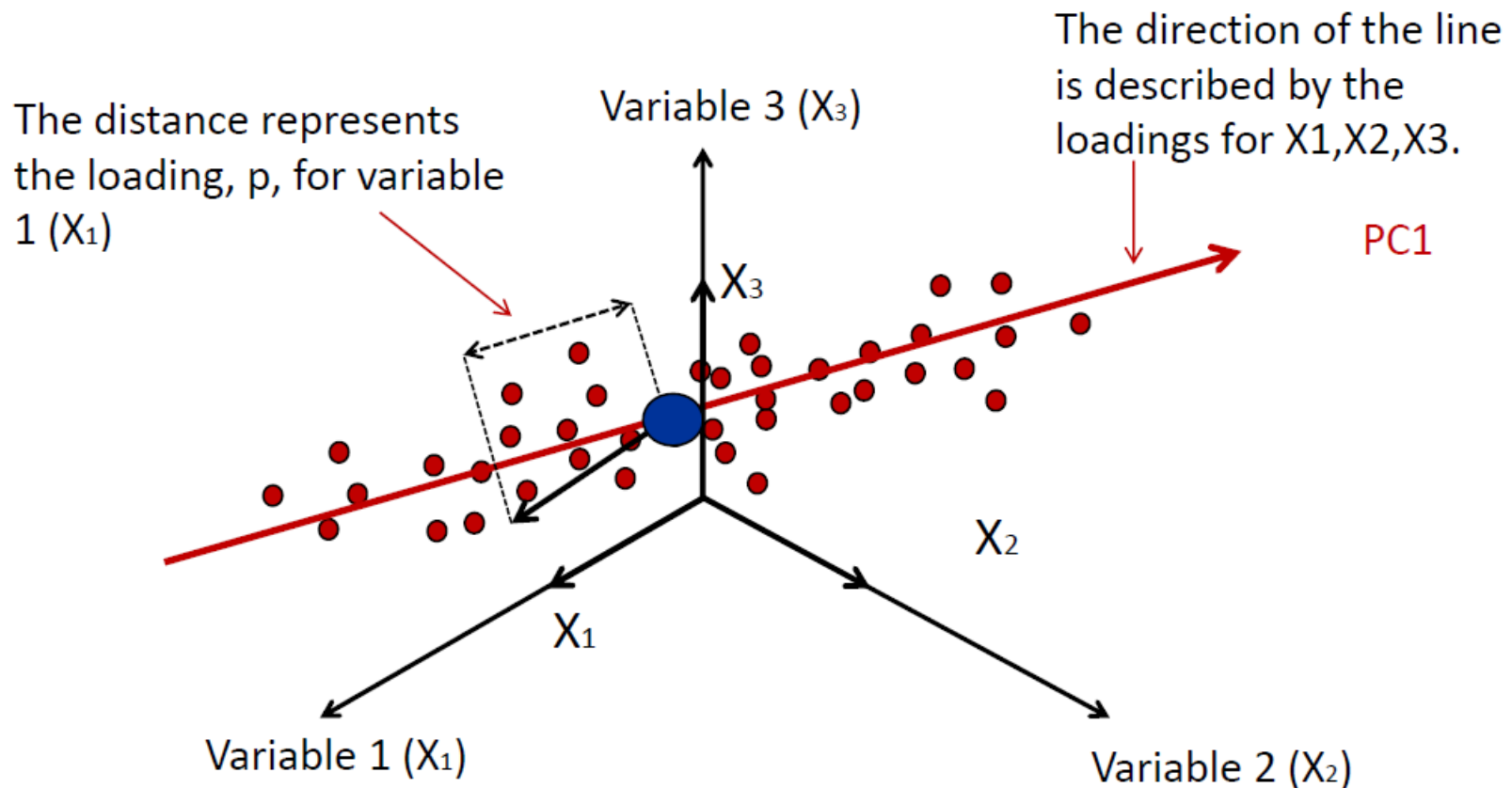
- Score plot – low dimensional summary of samples



# Review of PCA

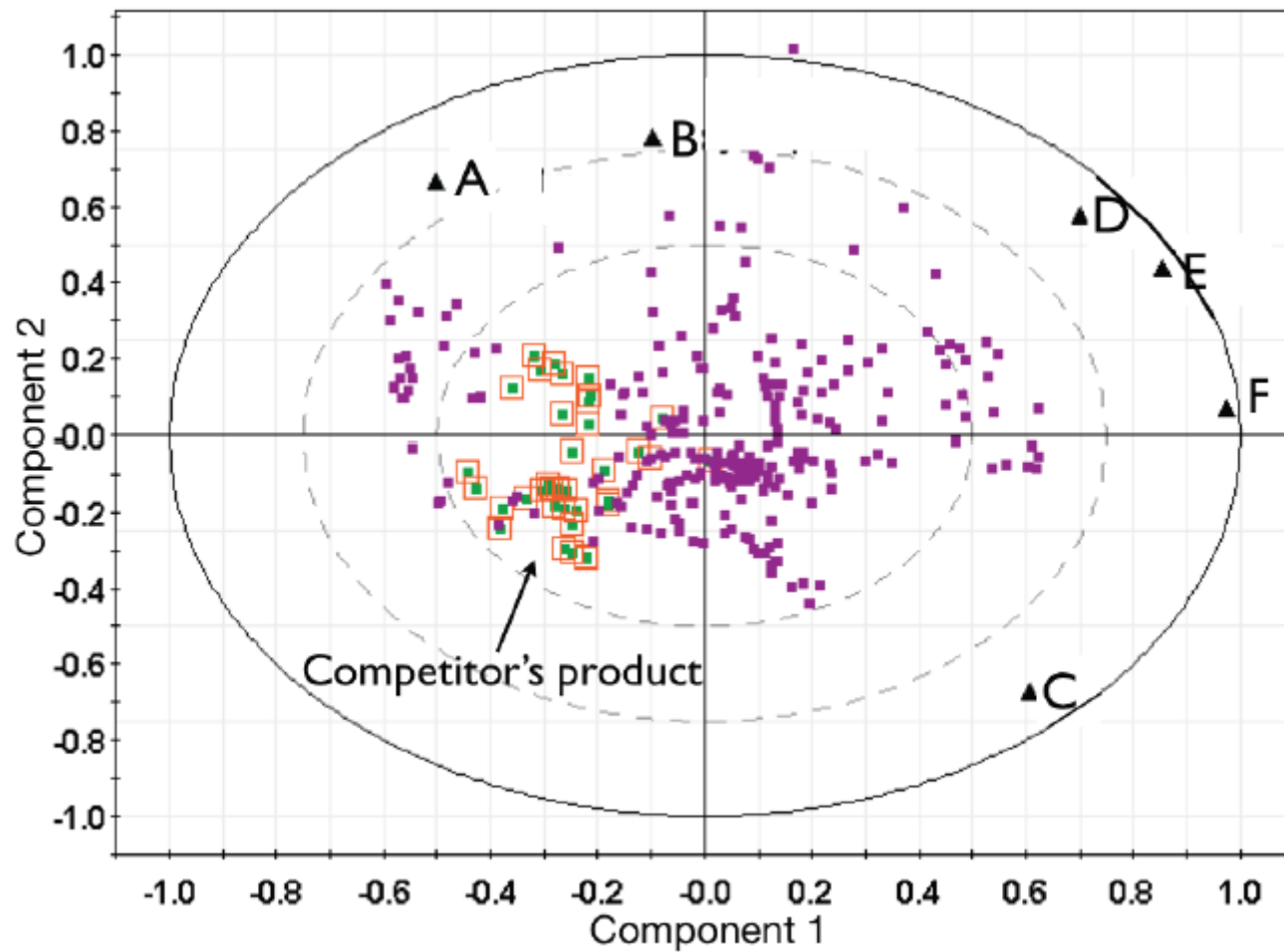
- What is loading?

**Coefficients in the linear combination**  $PC1 = a_1 X_1 + a_2 X_2 + a_3 X_3$



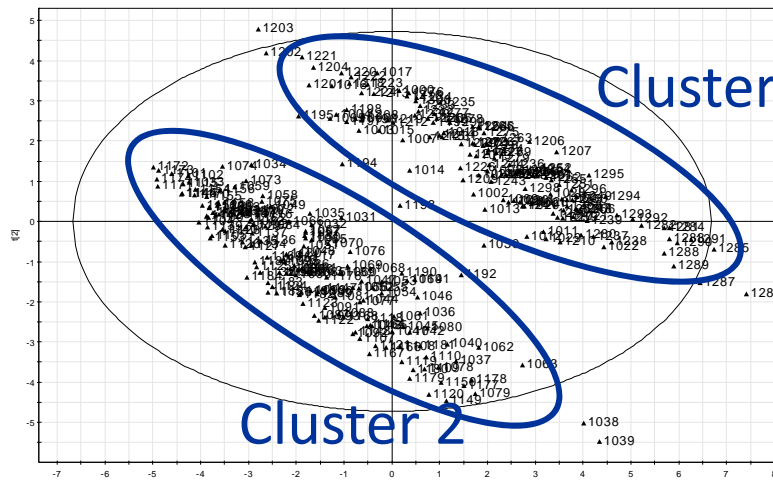
# Use of PCA

- Improved Process Understanding

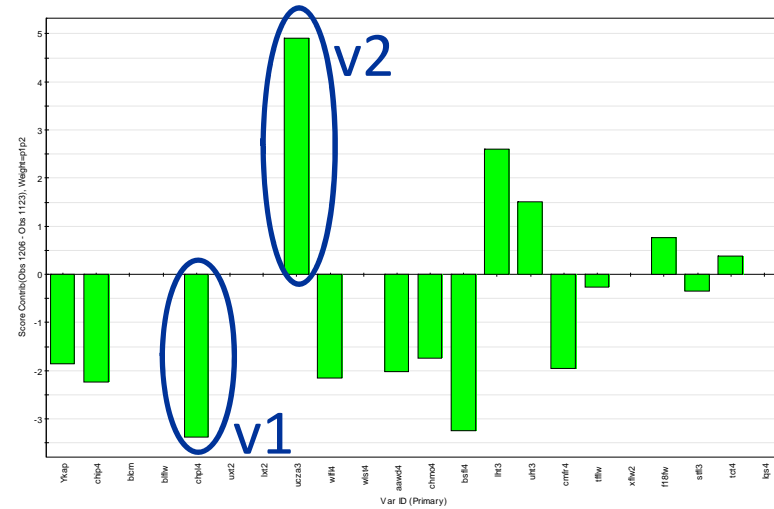


# Use of PCA

- Troubleshooting Process Problem



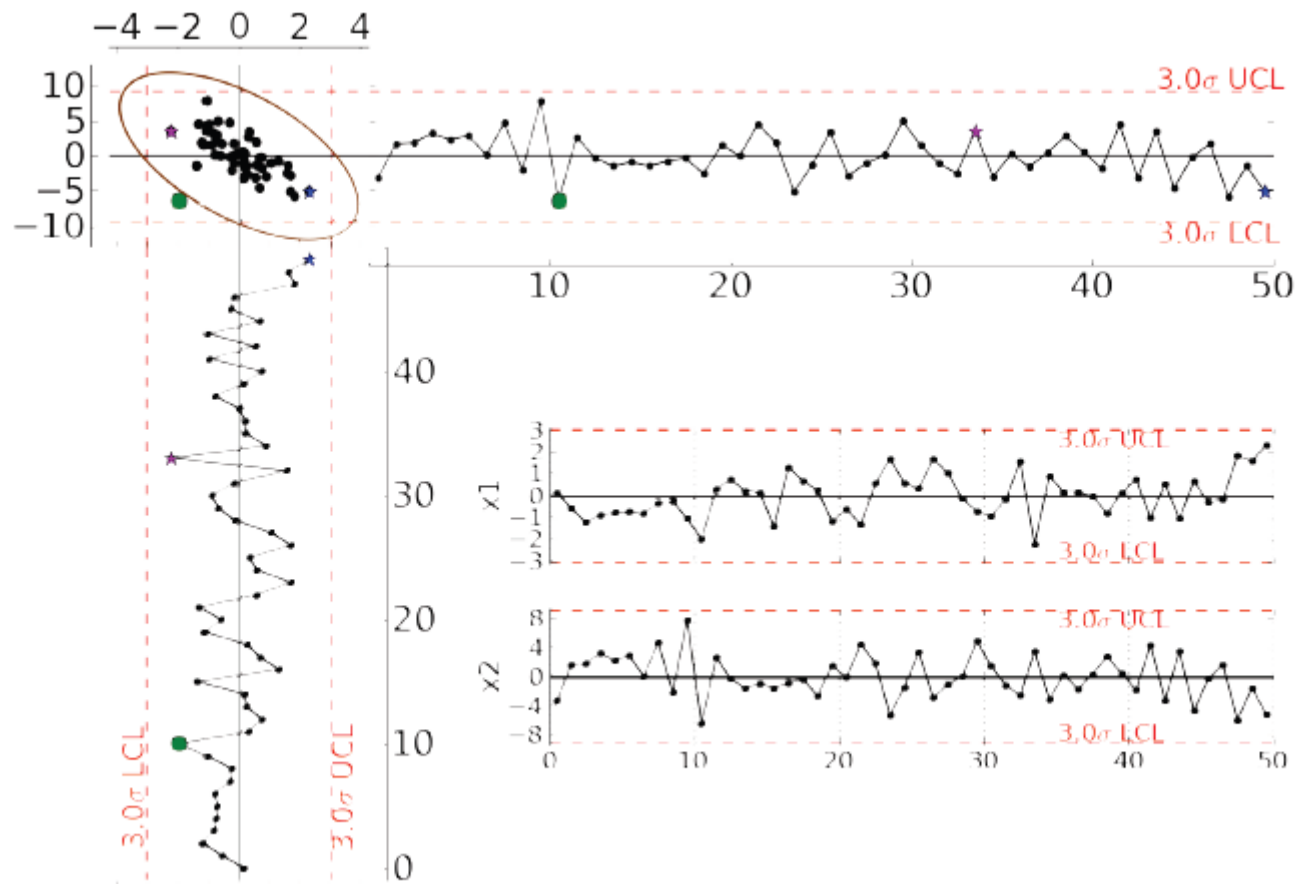
PCA score plot



PCA Contribution plot

# Use of PCA

- Multivariate Statistical Process Control (MSPC)



## In the next lecture

- Tutorials
- NIPALS algorithm
- A bit more on PCA
- Assignment #1