

1.

Taylor

$$f(x + \Delta x) = f(x) + (\Delta x)f'(x) + \frac{(\Delta x)^2}{2!}f''(x) + \frac{(\Delta x)^3}{3!}f'''(x) + \dots \quad (1)$$

$$f(x - \Delta x) = f(x) - (\Delta x)f'(x) + \frac{(\Delta x)^2}{2!}f''(x) - \frac{(\Delta x)^3}{3!}f'''(x) + \dots \quad (2)$$

(1) 2

$$f'(x) \approx \frac{f(x + \Delta x) - f(x)}{\Delta x} \quad : 1$$

(2) 2

$$f'(x) \approx \frac{f(x) - f(x - \Delta x)}{\Delta x} \quad : 1$$

(1) (2) $(\Delta x)^2$, 3

$$f'(x) \approx \frac{f(x + \Delta x) - f(x - \Delta x)}{2\Delta x} \quad : 1$$

2

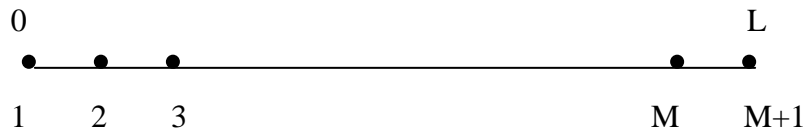
(1) (2) 4

$$f''(x) \approx \frac{f(x + \Delta x) - 2f(x) + f(x - \Delta x)}{(\Delta x)^2} \quad : 2$$

$$k \frac{d^2T}{dx^2} + g(x) = 0$$

$$x = 0 \quad T = T_0$$

$$x = L \quad T = T_L$$



$$1 \quad T_1 = T_0, M+1 \quad T_{M+1} = T_L$$

2

$$\frac{T_{i+1} - 2T_i + T_{i-1}}{(\Delta x)^2} = -\frac{g(x_i)}{k}$$

i=2

$$T_3 - 2T_2 = -\frac{g(x_2)}{k}(\Delta x)^2 - T_1 (= T_0)$$

i=M

$$-2T_M + T_{M-1} = -\frac{g(x_M)}{k}(\Delta x)^2 - T_{M+1} (= T_L)$$

i=3,4 ... M-1

$$T_{i+1} - 2T_i + T_{i-1} = -\frac{g(x_i)}{k}(\Delta x)^2$$

$$\begin{pmatrix} -2 & 1 & 0 & 0 & 0 & \cdots & 0 \\ 1 & -2 & 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & -2 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & -2 & 1 & \cdots & 0 \\ \vdots & \vdots & 0 & 1 & \ddots & 1 & \vdots \\ 0 & 0 & \vdots & 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & -2 \end{pmatrix} \begin{pmatrix} T_2 \\ T_3 \\ T_4 \\ \vdots \\ T_{M-2} \\ T_{M-1} \\ T_M \end{pmatrix} = \begin{pmatrix} -g(x_2)(\Delta x)^2/k - T_0 \\ -g(x_3)(\Delta x)^2/k \\ -g(x_4)(\Delta x)^2/k \\ \vdots \\ -g(x_{M-2})(\Delta x)^2/k \\ -g(x_{M-1})(\Delta x)^2/k \\ -g(x_M)(\Delta x)^2/k - T_{M+1} \end{pmatrix}$$

가

(i)

$$x=0 \quad -k \frac{dT}{dx} = q_0$$

$$x=0 \quad x = \frac{\Delta x}{2}$$

$$\int_0^{\frac{\Delta x}{2}} k \frac{d^2T}{dx^2} + g(x)dx = 0$$

$$\int_0^{\frac{\Delta x}{2}} g(x)dx = -k \frac{dT}{dx} \Big|_0^{\frac{\Delta x}{2}} = -k \frac{dT}{dx} \Big|_{\frac{\Delta x}{2}} - q_0$$

$$\frac{dT}{dx} \Big|_{\frac{\Delta x}{2}} \approx \frac{T_2 - T_1}{\Delta x} \quad ; 1$$

$$\int_0^{\frac{\Delta x}{2}} g(x)dx = -k \frac{T_2 - T_1}{\Delta x} - q_0$$

$$\int_0^{\frac{\Delta x}{2}} g(x)dx \approx g_1 \frac{\Delta x}{2}$$

$$g_1 \frac{\Delta x}{2} = -k \frac{T_2 - T_1}{\Delta x} - q_0$$

(ii) -

$$x = L \quad -k \frac{dT}{dx} = h(T - T_\infty)$$

$$x = L - \frac{\Delta x}{2} \quad x=L$$

$$\int_{L-\frac{\Delta x}{2}}^L k \frac{d^2T}{dx^2} + g(x) dx = 0$$

$$\int_{L-\frac{\Delta x}{2}}^L g(x) dx = -k \left. \frac{dT}{dx} \right|_{L-\frac{\Delta x}{2}}^L = -k \left. \frac{dT}{dx} \right|_L + k \left. \frac{dT}{dx} \right|_{L-\frac{\Delta x}{2}}$$

$$-k \left. \frac{dT}{dx} \right|_L = h(T|_L - T_\infty)$$

$$\left. \frac{dT}{dx} \right|_{L-\frac{\Delta x}{2}} \approx \frac{T_{M+1} - T_M}{\Delta x} \quad : 1$$

$$\int_{L-\frac{\Delta x}{2}}^L g(x) dx = h(T_{M+1} - T_\infty) + k \frac{T_{M+1} - T_M}{\Delta x}$$

$$\int_{L-\frac{\Delta x}{2}}^L g(x) dx \approx g_{M+1} \frac{\Delta x}{2}$$

$$g_{M+1} \frac{\Delta x}{2} = h(T_{M+1} - T_\infty) + k \frac{T_{M+1} - T_M}{\Delta x}$$

가 T_1

T_{M+1}
가 .

2.

가 .

가

가 .
가 .

$$k \frac{d^2 T}{dx^2} + g(x) = 0$$

$$x = 0 \quad T = T_0$$

$$x = L \quad T = T_L$$

$$x=0 \quad \frac{dT}{dx} \text{ 가 } \quad \text{가}$$

$$x=0 \quad \frac{dT}{dx} = A \quad \text{가}$$

$$x=L \quad T \quad \text{가} \quad x=0$$

$$\frac{dT}{dx} = A \text{ 가} \quad \text{가} \quad \text{가} \quad \text{가} \quad \text{A}$$

가 가

$$\frac{\partial T}{\partial t} = \alpha \frac{d^2 T}{dx^2}$$

$$x = 0 \quad T = T_0$$

$$x = L \quad T = T_L$$

$$x = 0 \quad T = f(x)$$

, (x)

$$\frac{T_j^{i+1} - T_j^i}{\Delta t} = \alpha \frac{T_{j+1}^i - 2T_j^i + T_{j-1}^i}{\Delta x^2}$$

$$T_j^{i+1} = T_{j+1}^i \left(\frac{\alpha \Delta t}{\Delta x^2} \right) - \left(\frac{\alpha \Delta t}{\Delta x^2} - 1 \right) T_j^i + \left(\frac{\alpha \Delta t}{\Delta x^2} \right) T_{j-1}^i \quad \text{가}$$

$$\left(\frac{\alpha \Delta t}{\Delta x^2} - 1 \right) \leq 0$$

가

$$\frac{\partial T_j}{\partial t} = \alpha \frac{T_{j+1} - 2T_j + T_{j-1}}{\Delta x^2}$$

x

M+1

M+1

(method of lines)