Chapter 2

APPLICATION AND CASE STUDIES

Outline

- SBR Semi-Batch Reactor System: Monitoring
- Batch Pulp Digester: Inferential Kappa Number Control
- Nylon 6,6 Autoclave: Monitoring & Inferential Control of Quality Variables
- Continuous Pulp Digester: Inferential Kappa Number Control

2.1 PCA MONITORING OF AN SBR SEMI-BATCH REACTOR SYSTEM

2.1.1 INTRODUCTION

Background

- In operating batch reaction systems, certain *abnormalities* (e.g., increased feed impurity level, catalyst poisonging, instrumentation malfunctioning) develop that eventually throw the quality completely off spec.
- It is desirable to catch these incipient faults quickly so that the problem can be rectified.
- It is desirable not to rely on lab measurements for this purpose since this will introduce significant delays.

Key Idea

- Use more easily measured process variable trends to classify between normal batches and abnormal batches.
- The key problem is to extract out the key identifying features (*finger* prints) from trajectories of large amount of variables.

Appication

• An SBR Polymerization Reactor.

2.1.2 PROBLEM DESCCRIPTION

Process / Problem Characteristics

• Reaction:

Styrene + Butadiene $\longrightarrow^{\text{polymerization}}$ Latex Rubber

- Emulsion Polymerization
- The reactor is initially charged with seed SBR particles, initiator, chain-transfer agent, emulsifier, a small amount of styrene and butadiene monomers.
- Batch duration is 1000 minutes.
- The following measurements are available with 5 minute interval:
 - flow rates of styrene
 - flow rates of butadiene
 - temperature of feed
 - temperature of reactor
 - temperature of cooling water
 - temperature of reactor jacket
 - density of latex in the reactor
 - total conversion (an estimate)
 - instantaneous rate of energy release (an estimate)

Available Data

• 50 batch runs with typical random variations in base case conditions (such as initial charge of seed latex, amount of chain transfer agent and level of impurities).

- Two additional batches with "unusual disturbances."
 - impurity of 30% above that of the base case was introduced in the butadiene feed at the beginning of the batch.
 - impurity of 50% above that of the base case was introduced in the butadiene feed at the halfway mark.



2.1.3 RESULTS

End-Of-Batch Principal Component Analysis

• Establish the mean trajetory for each variable and compute the deviation trajectory.



- Normalize each variable with its variance.
- Perform "lifting", that is, stack all the trajectories into a common vector to obtain a single vector Y for each batch. Then, form a matrix Y by aligning Y for the entire 50 batches.

Note the dimension of \mathcal{Y} is 9×200 . Clearly there are only a few modes of variations in this vector.

• Determine the principal component directions (eigenvectors of Y with significant eigenvalues). Three components were judged to be sufficient.

$$Y = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 & \cdots & v_{1800} \end{bmatrix} \begin{bmatrix} \sigma_1 & & & & \\ & \sigma_2 & & & \\ & & \sigma_3 & & & \\ & & & \sigma_4 & & \\ & & & & \ddots & \\ & & & & \sigma_{1800} \end{bmatrix} \begin{bmatrix} v_1^T \\ v_2^T \\ v_3^T \\ \vdots \\ v_{1800}^T \end{bmatrix}$$

• Compute the principal component score variables for each batch:

$$t_i(j) = v_i^T \mathcal{Y}(j), \qquad i = 1, \cdots, 3 \qquad j = 1, \cdots, 50$$

The first two P.C. scores for the 50 batches and the two bad batches are plotted below:



Compute the covariance matrix (diagonal) R_t for the P.C.'s. Establish the 95% and 99% confidence limits (ellipses) for the P.C.'s.

One can also use Hotelling Statistics:

$$D = t^T R_t^{-1} t \frac{N(N-m)}{m(N^2-1)} \sim F_{m,N-m}$$

Here $t = [t_1, t_2, t_3]^T$ and N = 50 and m = 3.

• Compute the residuals and establish the 95% and 99% confidence limits for the square sum (assuming normality of the underlying distribution). The SPE (sum of the squares of the residuals) for each batch is plotted against the confidence limits:



During-Batch Principal Component Analysis

• The main issue in applying the PC monitoring during a batch is what to do with the missing future data.



Handling missing measurement

Options are:

- Assume for all the variables that the future deviation will be zero.
- Assume for each variable that the current level of deviation will continue until the end of batch.
- Use statistical correlation to estimate the future deviation.

We will denote the lifted vector at time t with missing future measurements filled in as $\hat{\mathcal{Y}}_t(j)$, where t and j denote the time and batch index.

- For each time step, the confidence limits for the SPE and P.C.'s can be established.
- Now, at each time step for each batch, compute the P.C.s and SPE and compare against the confidence intervals.

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TIME







